

Some smooth applications of non-smooth Ricci
curvature lower bounds
2nd Part: Smooth applications

Andrea Mondino (University of Warwick)

Workshop in Geometric Analysis
Institut Henri Poincaré
19th December 2018

Plan of the talk

GOAL: discuss some recent geometric applications to *smooth* Riemannian manifolds of *non-smooth* synthetic Ricci curvature lower bounds

GOAL: discuss some recent geometric applications to *smooth* Riemannian manifolds of *non-smooth* synthetic Ricci curvature lower bounds

- ▶ Quantitative Levy-Gromov isoperimetric inequality,

Plan of the talk

GOAL: discuss some recent geometric applications to *smooth* Riemannian manifolds of *non-smooth* synthetic Ricci curvature lower bounds

- ▶ Quantitative Levy-Gromov isoperimetric inequality,
- ▶ Almost Euclidean isoperimetric inequality in a small ball in a manifold with Ricci curvature bounded below, motivated by Ricci flow.

Plan of the talk

GOAL: discuss some recent geometric applications to *smooth* Riemannian manifolds of *non-smooth* synthetic Ricci curvature lower bounds

- ▶ Quantitative Levy-Gromov isoperimetric inequality,
- ▶ Almost Euclidean isoperimetric inequality in a small ball in a manifold with Ricci curvature bounded below, motivated by Ricci flow.

Isoperimetric problem

One of oldest problems in mathematics, roots in myths of 2000 years ago (Queen Dido's problem).

Q: Given a space X and a volume v , what is the minimal amount of (boundary) area needed to enclose the volume $v > 0$?

Isoperimetric problem

One of oldest problems in mathematics, roots in myths of 2000 years ago (Queen Dido's problem).

Q: Given a space X and a volume v , what is the minimal amount of (boundary) area needed to enclose the volume $v > 0$?

Examples

- ▶ $X = \mathbb{R}^n \rightsquigarrow$ Euclidean isoperimetric inequality:
For all $E \subset \mathbb{R}^n$ it holds $|\partial E| \geq |\partial B|$ where B is a round ball
s.t. $|B| = |E|$.

Isoperimetric problem

One of oldest problems in mathematics, roots in myths of 2000 years ago (Queen Dido's problem).

Q: Given a space X and a volume v , what is the minimal amount of (boundary) area needed to enclose the volume $v > 0$?

Examples

- ▶ $X = \mathbb{R}^n \rightsquigarrow$ Euclidean isoperimetric inequality:
For all $E \subset \mathbb{R}^n$ it holds $|\partial E| \geq |\partial B|$ where B is a round ball s.t. $|B| = |E|$.
- ▶ $X = \mathbb{S}^n$ analogous:
For all $E \subset \mathbb{S}^n$ it holds $|\partial E| \geq |\partial B|$ where B is a metric ball (i.e. a spherical cap) s.t. $|B| = |E|$

Isoperimetric problem

One of oldest problems in mathematics, roots in myths of 2000 years ago (Queen Dido's problem).

Q: Given a space X and a volume v , what is the minimal amount of (boundary) area needed to enclose the volume $v > 0$?

Examples

- ▶ $X = \mathbb{R}^n \rightsquigarrow$ Euclidean isoperimetric inequality:
For all $E \subset \mathbb{R}^n$ it holds $|\partial E| \geq |\partial B|$ where B is a round ball s.t. $|B| = |E|$.
- ▶ $X = \mathbb{S}^n$ analogous:
For all $E \subset \mathbb{S}^n$ it holds $|\partial E| \geq |\partial B|$ where B is a metric ball (i.e. a spherical cap) s.t. $|B| = |E|$

RK: In both of the examples the space is fixed (Euclidean space of Sphere), such a space contains a model subset (metric ball), and any subset of the space is compared with such a model subset.

Levy-Gromov inequality

Besides the euclidean one, probably the most famous isoperimetric inequality is the Levy-Gromov isoperimetric inequality:

Levy-Gromov Isoperimetric inequality

Let (M^n, g) be a Riemannian manifold with $Ric_g \geq (n - 1)g$ and $E \subset M$ domain with smooth boundary ∂E .

Levy-Gromov inequality

Besides the euclidean one, probably the most famous isoperimetric inequality is the Levy-Gromov isoperimetric inequality:

Levy-Gromov Isoperimetric inequality

Let (M^n, g) be a Riemannian manifold with $Ric_g \geq (n - 1)g$ and $E \subset M$ domain with smooth boundary ∂E .

Let \mathbb{S}^n be the round sphere of unit radius (in particular $Ric \equiv n - 1$), and $B \subset \mathbb{S}^n$ be a metric ball s.t. $\frac{|E|}{|M|} = \frac{|B|}{|\mathbb{S}^n|}$.

Levy-Gromov inequality

Besides the euclidean one, probably the most famous isoperimetric inequality is the Levy-Gromov isoperimetric inequality:

Levy-Gromov Isoperimetric inequality

Let (M^n, g) be a Riemannian manifold with $Ric_g \geq (n-1)g$ and $E \subset M$ domain with smooth boundary ∂E .

Let \mathbb{S}^n be the round sphere of unit radius (in particular $Ric \equiv n-1$), and $B \subset \mathbb{S}^n$ be a metric ball s.t. $\frac{|E|}{|M|} = \frac{|B|}{|\mathbb{S}^n|}$. Then

$$\frac{|\partial E|}{|M|} \geq \frac{|\partial B|}{|\mathbb{S}^n|}$$

Levy-Gromov inequality

Besides the euclidean one, probably the most famous isoperimetric inequality is the Levy-Gromov isoperimetric inequality:

Levy-Gromov Isoperimetric inequality

Let (M^n, g) be a Riemannian manifold with $Ric_g \geq (n-1)g$ and $E \subset M$ domain with smooth boundary ∂E .

Let \mathbb{S}^n be the round sphere of unit radius (in particular $Ric \equiv n-1$), and $B \subset \mathbb{S}^n$ be a metric ball s.t. $\frac{|E|}{|M|} = \frac{|B|}{|\mathbb{S}^n|}$. Then

$$\frac{|\partial E|}{|M|} \geq \frac{|\partial B|}{|\mathbb{S}^n|}$$

RK. (1) In the (LGI) the space is NOT fixed: any subset in any manifold with $Ric \geq n-1$ is compared with the **model subset** (i.e. spherical cap) in the **model space** (i.e. the sphere).

Levy-Gromov inequality

Besides the euclidean one, probably the most famous isoperimetric inequality is the Levy-Gromov isoperimetric inequality:

Levy-Gromov Isoperimetric inequality

Let (M^n, g) be a Riemannian manifold with $Ric_g \geq (n-1)g$ and $E \subset M$ domain with smooth boundary ∂E .

Let \mathbb{S}^n be the round sphere of unit radius (in particular

$Ric \equiv n-1$), and $B \subset \mathbb{S}^n$ be a metric ball s.t. $\frac{|E|}{|M|} = \frac{|B|}{|\mathbb{S}^n|}$. Then

$$\frac{|\partial E|}{|M|} \geq \frac{|\partial B|}{|\mathbb{S}^n|}$$

RK. (1) In the (LGI) the space is NOT fixed: any subset in any manifold with $Ric \geq n-1$ is compared with the **model subset** (i.e. spherical cap) in the **model space** (i.e. the sphere).

(2) (LGI) is **global in the space**, i.e. it does not depend just on E but also on $M \setminus E$: if one changes the space locally outside of E , the lhs in (LGI) may change since $|M|$ may change.

Equivalent way to state LG inequality in terms of isoperimetric profile

Equivalent way to state LG inequality in terms of isoperimetric profile

- ▶ Given a Riemannian manifold (M, g) , define its *isoperimetric profile function* as

$$\mathcal{I}_{(M,g)}(v) := \inf \left\{ \frac{|\partial E|}{|M|} : \frac{|E|}{|M|} = v \right\}, \quad \forall v \in [0, 1].$$

Equivalent way to state LG inequality in terms of isoperimetric profile

- ▶ Given a Riemannian manifold (M, g) , define its *isoperimetric profile function* as

$$\mathcal{I}_{(M,g)}(v) := \inf \left\{ \frac{|\partial E|}{|M|} : \frac{|E|}{|M|} = v \right\}, \quad \forall v \in [0, 1].$$

- ▶ Levy-Gromov Inequality can be stated as: Given (M^n, g) with $\text{Ric}_g \geq (n-1)g$ then

$$\mathcal{I}_{(M,g)}(v) \geq \mathcal{I}_{\mathbb{S}^n}(v), \quad \forall v \in [0, 1].$$

Rigidity and almost rigidity in the Levy-Gromov inequality

- ▶ **Rigidity:** If there exists $E \subset M$ with $\frac{|E|}{|M|} = v \in (0, 1)$ satisfying $\frac{|\partial E|}{|M|} = \mathcal{I}_{(M,g)}(v) = \mathcal{I}_{\mathbb{S}^n}(v)$, then
 - 1) $(M^n, g) \simeq \mathbb{S}^n$ isometric
 - 2) $E \simeq B$ metric ball.

Rigidity and almost rigidity in the Levy-Gromov inequality

- ▶ **Rigidity:** If there exists $E \subset M$ with $\frac{|E|}{|M|} = v \in (0, 1)$ satisfying $\frac{|\partial E|}{|M|} = \mathcal{I}_{(M,g)}(v) = \mathcal{I}_{\mathbb{S}^n}(v)$, then
 - 1) $(M^n, g) \simeq \mathbb{S}^n$ isometric
 - 2) $E \simeq B$ metric ball.
- ▶ **Question: Stability?** i.e. If “=” in (LGI) is almost attained,
 - Q1) What can we say on (M^n, g) ? Is it close to a sphere? In which sense?
 - Q2) What can we say on E ? Is it close to a metric ball? In which sense?

About Question Q1

About Question Q1

THM 1 (Particular case of Berard-Besson-Gallot, Inv. Math, 1985)

Given (M^n, g) with $Ric_g \geq (n-1)g$ and $\text{diam}(M) = D$ (recall from Bonnet-Myers $D \in (0, \pi)$) then

$$\frac{\mathcal{I}_{(M,g)}(v)}{\mathcal{I}_{\mathbb{S}^n}(v)} \geq \left(\frac{\int_0^{\pi/2} (\cos t)^{n-1} dt}{\int_0^{D/2} (\cos t)^{n-1} dt} \right)^{1/n}$$

About Question Q1

THM 1 (Particular case of Berard-Besson-Gallot, Inv. Math, 1985)

Given (M^n, g) with $Ric_g \geq (n-1)g$ and $\text{diam}(M) = D$ (recall from Bonnet-Myers $D \in (0, \pi)$) then

$$\frac{\mathcal{I}_{(M,g)}(v)}{\mathcal{I}_{\mathbb{S}^n}(v)} \geq \left(\frac{\int_0^{\pi/2} (\cos t)^{n-1} dt}{\int_0^{D/2} (\cos t)^{n-1} dt} \right)^{1/n}$$

RK:

- 1) rhs is ≥ 1 so the result sharpens the classical LGI
- 2) It follows that there exists $C_{n,v} > 0$ such that if for some $v \in (0, 1)$ it holds $\mathcal{I}_{(M,g)}(v) \leq \mathcal{I}_{\mathbb{S}^n}(v) + \delta$, then

$$\pi - D \leq C_{n,v} \delta^{1/n}.$$

Answering Question 2 in Euclidean setting

Quantitative Euclidean Isoperimetric Inequality

(Fusco-Maggi-Pratelli, Annals of Math. 2008)

There exists $C_n > 0$ such that for every $E \subset \mathbb{R}^n$ there exists a round ball $B \subset \mathbb{R}^n$ with $|E| = |B|$ and

$$\frac{|E \Delta B|}{|E|} \leq C_n \left(\frac{|\partial E|}{|\partial B|} - 1 \right)^{1/2}$$

Answering Question 2 in Euclidean setting

Quantitative Euclidean Isoperimetric Inequality

(Fusco-Maggi-Pratelli, Annals of Math. 2008)

There exists $C_n > 0$ such that for every $E \subset \mathbb{R}^n$ there exists a round ball $B \subset \mathbb{R}^n$ with $|E| = |B|$ and

$$\frac{|E \Delta B|}{|E|} \leq C_n \left(\frac{|\partial E|}{|\partial B|} - 1 \right)^{1/2}$$

RK: 1) the rhs is the so-called “isoperimetric deficit” and is zero iff E is a ball (by rigidity in Ell).

2) The proof of FMP is via a “quantitative symmetrization”.

3) Alternative proof of the result via Brenier L^2 -Optimal Transport map (by Figalli-Maggi-Pratelli, Inv. Math. 2010) and via regularity theory and selection principle (Cicalese-Leonardi, ARMA 2012).

Answering Question 2 in spherical setting

Quantitative Spherical Isoperimetric Inequality

(Bogelein-Duzaar-Fusco, Adv. Calc. Var. 2015)

For every $\nu \in (0, 1)$ and every $n \geq 2$ there exists $C_{n,\nu} > 0$ with the following property.

For every $E \subset \mathbb{S}^n$ with $\frac{|E|}{|\mathbb{S}^n|} = \nu$ there exists a metric ball $B \subset \mathbb{S}^n$ with $|B| = |E|$ such that

$$|E \Delta B| \leq C_{n,\nu} \left(\frac{|\partial E|}{|\mathbb{S}^n|} - \mathcal{I}_{\mathbb{S}^n}(\nu) \right)^{1/2}$$

Answering Question 2 in spherical setting

Quantitative Spherical Isoperimetric Inequality

(Bogelein-Duzaar-Fusco, Adv. Calc. Var. 2015)

For every $\nu \in (0, 1)$ and every $n \geq 2$ there exists $C_{n,\nu} > 0$ with the following property.

For every $E \subset \mathbb{S}^n$ with $\frac{|E|}{|\mathbb{S}^n|} = \nu$ there exists a metric ball $B \subset \mathbb{S}^n$ with $|B| = |E|$ such that

$$|E \Delta B| \leq C_{n,\nu} \left(\frac{|\partial E|}{|\mathbb{S}^n|} - \mathcal{I}_{\mathbb{S}^n}(\nu) \right)^{1/2}$$

Proof: along the same lines of Cicalese-Leonardi's selection principle.

Difficulties about Question 2: quantitative Levy-Gromov inequality

The above quantitative isoperimetric inequalities are for a **fixed** space (\mathbb{R}^n or \mathbb{S}^n), with the **highest possible degree of symmetry**.

LGI is for any (M^n, g) with $Ric_g \geq (n-1)g$

↪ No fixed space and no symmetry.

↪ The above approaches seem not to be applicable:

Difficulties about Question 2: quantitative Levy-Gromov inequality

The above quantitative isoperimetric inequalities are for a **fixed** space (\mathbb{R}^n or \mathbb{S}^n), with the **highest possible degree of symmetry**.

LGI is for any (M^n, g) with $Ric_g \geq (n-1)g$

↪ No fixed space and no symmetry.

↪ The above approaches seem not to be applicable:

- ▶ Symmetrization (FMP): since M is not symmetric it makes little sense to speak of symmetrization.
- ▶ Brenier Map, L^2 -OT (FMP): works in \mathbb{R}^n but already in \mathbb{S}^n it is an open problem to prove Spherical Isoperimetric Inequality via Brenier Map.
- ▶ Selection Principle (CL): would need smooth convergence of metrics while here the natural convergence is Gromov-Hausdorff.

Difficulties about Question 2: quantitative Levy-Gromov inequality

The above quantitative isoperimetric inequalities are for a **fixed** space (\mathbb{R}^n or \mathbb{S}^n), with the **highest possible degree of symmetry**. LGI is for any (M^n, g) with $Ric_g \geq (n-1)g$

↪ No fixed space and no symmetry.

↪ The above approaches seem not to be applicable:

- ▶ Symmetrization (FMP): since M is not symmetric it makes little sense to speak of symmetrization.
- ▶ Brenier Map, L^2 -OT (FMP): works in \mathbb{R}^n but already in \mathbb{S}^n it is an open problem to prove Spherical Isoperimetric Inequality via Brenier Map.
- ▶ Selection Principle (CL): would need smooth convergence of metrics while here the natural convergence is Gromov-Hausdorff.

↪ Novel approach: localization via L^1 -Optimal Transport.

The result: quantitative Levy-Gromov inequality

THM 2 (Cavalletti-Maggi-M. in press in CPAM)

For every $\nu \in (0, 1)$ and $n \geq 2$ there exists $C_{n,\nu} > 0$ with the following properties.

Let (M^n, g) be with $Ric_g \geq (n-1)g$. For every $E \subset M$ with $\frac{|E|}{|M|} = \nu$ there exists a metric ball $B \subset M$ with $|B| = |E|$ such that

$$|E \Delta B| \leq C_{n,\nu} \left(\frac{|\partial E|}{|M|} - \mathcal{I}_{\mathbb{S}^n}(\nu) \right)^{\frac{n}{n^2+n-1}}$$

In particular, if $E \subset M$ is an isoperimetric subset with $\frac{|E|}{|M|} = \nu$, then

$$|E \Delta B| \leq C_{n,\nu} \left(\mathcal{I}_{(M,g)}(\nu) - \mathcal{I}_{\mathbb{S}^n}(\nu) \right)^{\frac{n}{n^2+n-1}}$$

The result: quantitative Levy-Gromov inequality

THM 2 (Cavalletti-Maggi-M. in press in CPAM)

For every $\nu \in (0, 1)$ and $n \geq 2$ there exists $C_{n,\nu} > 0$ with the following properties.

Let (M^n, g) be with $Ric_g \geq (n-1)g$. For every $E \subset M$ with $\frac{|E|}{|M|} = \nu$ there exists a metric ball $B \subset M$ with $|B| = |E|$ such that

$$|E \Delta B| \leq C_{n,\nu} \left(\frac{|\partial E|}{|M|} - \mathcal{I}_{\mathbb{S}^n}(\nu) \right)^{\frac{n}{n^2+n-1}}$$

In particular, if $E \subset M$ is an isoperimetric subset with $\frac{|E|}{|M|} = \nu$, then

$$|E \Delta B| \leq C_{n,\nu} \left(\mathcal{I}_{(M,g)}(\nu) - \mathcal{I}_{\mathbb{S}^n}(\nu) \right)^{\frac{n}{n^2+n-1}}$$

RK Difference with QEII or QSII: here $E \subset M$ and $|\partial E|$ is compared with $\mathcal{I}_{\mathbb{S}^n}$ (not of $\mathcal{I}_{(M,g)}$) via a “Levy-Gromov isoperimetric deficit”.

The result holds in higher generality

Actually we prove THM1 and THM 2 more generally for $RCD(N - 1, N)$ metric measure spaces. As we saw in the first lecture, examples entering this class of spaces:

- ▶ mGH-limits of Riemannian N -dimensional manifolds satisfying $Ric_g \geq (N - 1)g$.
- ▶ N -dimensional Alexandrov spaces with curvature ≥ 1 .

Part 2. Ricci flow, Perelman's Pseudo Locality Theorem and Almost euclidean isoperimetric inequalities.

Perelman's Pseudo-locality Theorem

THM [Theorem 10.1, Perelman's first Ricci flow paper 2002]

Perelman's Pseudo-locality Theorem

THM[Theorem 10.1, Perelman's first Ricci flow paper 2002] For every $\alpha > 0$ there exists $\delta > 0, \varepsilon > 0$ with the following property. Suppose we have a smooth solution to the Ricci flow $(g_{ij})_t = -2R_{ij}$, $0 \leq t \leq \varepsilon^2$, and assume that at $t = 0$ we have

$$R_{g_0}(x) \geq -1 \quad \& \quad |\partial\Omega|_{g_0} \geq (1 - \delta) c_n |\Omega|_{g_0}^{(n-1)/n}, \quad \forall x, \Omega \subset B_1(x_0),$$

where c_n is the euclidean isoperimetric constant.

Perelman's Pseudo-locality Theorem

THM[Theorem 10.1, Perelman's first Ricci flow paper 2002] For every $\alpha > 0$ there exists $\delta > 0, \varepsilon > 0$ with the following property. Suppose we have a smooth solution to the Ricci flow $(g_{ij})_t = -2R_{ij}$, $0 \leq t \leq \varepsilon^2$, and assume that at $t = 0$ we have

$$R_{g_0}(x) \geq -1 \quad \& \quad |\partial\Omega|_{g_0} \geq (1 - \delta) c_n |\Omega|_{g_0}^{(n-1)/n}, \quad \forall x, \Omega \subset B_1(x_0),$$

where c_n is the euclidean isoperimetric constant.

Then we have an estimate $|Rm|(x, t) \leq \alpha t^{-1} + \varepsilon^{-2}$ whenever $0 < t \leq \varepsilon^2$, $d_{g_t}(x, x_0) < \varepsilon$.

Perelman's Pseudo-locality Theorem

THM[Theorem 10.1, Perelman's first Ricci flow paper 2002] For every $\alpha > 0$ there exists $\delta > 0, \varepsilon > 0$ with the following property. Suppose we have a smooth solution to the Ricci flow $(g_{ij})_t = -2R_{ij}$, $0 \leq t \leq \varepsilon^2$, and assume that at $t = 0$ we have

$$R_{g_0}(x) \geq -1 \quad \& \quad |\partial\Omega|_{g_0} \geq (1 - \delta) c_n |\Omega|_{g_0}^{(n-1)/n}, \quad \forall x, \Omega \subset B_1(x_0),$$

where c_n is the euclidean isoperimetric constant.

Then we have an estimate $|Rm|(x, t) \leq \alpha t^{-1} + \varepsilon^{-2}$ whenever $0 < t \leq \varepsilon^2$, $d_{g_t}(x, x_0) < \varepsilon$.

RK: The non-linearity of Ricci flow here helps: if we have good geometric control on ball, and no assumptions outside, the Ricci flow for small times improves the geometric control in the ball regardless how bad the manifold is outside.

Perelman's Pseudo-locality Theorem

THM[Theorem 10.1, Perelman's first Ricci flow paper 2002] For every $\alpha > 0$ there exists $\delta > 0, \varepsilon > 0$ with the following property. Suppose we have a smooth solution to the Ricci flow $(g_{ij})_t = -2R_{ij}$, $0 \leq t \leq \varepsilon^2$, and assume that at $t = 0$ we have

$$R_{g_0}(x) \geq -1 \quad \& \quad |\partial\Omega|_{g_0} \geq (1 - \delta) c_n |\Omega|_{g_0}^{(n-1)/n}, \quad \forall x, \Omega \subset B_1(x_0),$$

where c_n is the euclidean isoperimetric constant.

Then we have an estimate $|Rm|(x, t) \leq \alpha t^{-1} + \varepsilon^{-2}$ whenever $0 < t \leq \varepsilon^2$, $d_{g_t}(x, x_0) < \varepsilon$.

RK: The non-linearity of Ricci flow here helps: if we have good geometric control on ball, and no assumptions outside, the Ricci flow for small times improves the geometric control in the ball regardless how bad the manifold is outside.

Perelman's Pseudo-locality Theorem revisited by Tian&Wang

THM[Tian-Wang JAMS 2015]

Perelman's Pseudo-locality Theorem revisited by Tian&Wang

THM[Tian-Wang JAMS 2015] For every $\alpha > 0$ there exists $\delta > 0, \varepsilon > 0$ with the following property. Suppose we have a smooth solution to the Ricci flow $(g_{ij})_t = -2R_{ij}$, $0 \leq t \leq \varepsilon^2$, and assume that at $t = 0$ we have

$$\text{Ric}_{g_0}(x) \geq -\delta^2 g_0 \text{ on } B_1(x_0) \quad \& \quad |B_1(x_0)|_{g_0} \geq (1 - \delta) \omega_n.$$

Perelman's Pseudo-locality Theorem revisited by Tian&Wang

THM[Tian-Wang JAMS 2015] For every $\alpha > 0$ there exists $\delta > 0, \varepsilon > 0$ with the following property. Suppose we have a smooth solution to the Ricci flow $(g_{ij})_t = -2R_{ij}$, $0 \leq t \leq \varepsilon^2$, and assume that at $t = 0$ we have

$$\text{Ric}_{g_0}(x) \geq -\delta^2 g_0 \text{ on } B_1(x_0) \quad \& \quad |B_1(x_0)|_{g_0} \geq (1 - \delta) \omega_n.$$

Then $|Rm|(x, t) \leq \alpha t^{-1} + \varepsilon^{-2}$ for $0 < t \leq \varepsilon^2$, $d_{g_t}(x, x_0) < \varepsilon$.

Perelman's Pseudo-locality Theorem revisited by Tian&Wang

THM[Tian-Wang JAMS 2015] For every $\alpha > 0$ there exists $\delta > 0, \varepsilon > 0$ with the following property. Suppose we have a smooth solution to the Ricci flow $(g_{ij})_t = -2R_{ij}$, $0 \leq t \leq \varepsilon^2$, and assume that at $t = 0$ we have

$$\text{Ric}_{g_0}(x) \geq -\delta^2 g_0 \text{ on } B_1(x_0) \quad \& \quad |B_1(x_0)|_{g_0} \geq (1 - \delta) \omega_n.$$

Then $|Rm|(x, t) \leq \alpha t^{-1} + \varepsilon^{-2}$ for $0 < t \leq \varepsilon^2$, $d_{g_t}(x, x_0) < \varepsilon$.

RK: - From Bishop Gromov we have $|B|_{g_0} \leq (1 + C\delta) \omega_n$, so the condition $|B|_{g_0} \geq (1 - \delta) \omega_n$ is an almost maximal volume assumption.

Perelman's Pseudo-locality Theorem revisited by Tian&Wang

THM[Tian-Wang JAMS 2015] For every $\alpha > 0$ there exists $\delta > 0, \varepsilon > 0$ with the following property. Suppose we have a smooth solution to the Ricci flow $(g_{ij})_t = -2R_{ij}$, $0 \leq t \leq \varepsilon^2$, and assume that at $t = 0$ we have

$$\text{Ric}_{g_0}(x) \geq -\delta^2 g_0 \text{ on } B_1(x_0) \quad \& \quad |B_1(x_0)|_{g_0} \geq (1 - \delta) \omega_n.$$

Then $|Rm|(x, t) \leq \alpha t^{-1} + \varepsilon^{-2}$ for $0 < t \leq \varepsilon^2$, $d_{g_t}(x, x_0) < \varepsilon$.

RK: - From Bishop Gromov we have $|B|_{g_0} \leq (1 + C\delta)\omega_n$, so the condition $|B|_{g_0} \geq (1 - \delta)\omega_n$ is an almost maximal volume assumption.

-The proof by Tian-Wang is highly technical and not at all a straightforward corollary of Perelman's Pseudolocality Theorem.

Perelman's Pseudo-locality Theorem revisited by Tian&Wang

THM[Tian-Wang JAMS 2015] For every $\alpha > 0$ there exists $\delta > 0, \varepsilon > 0$ with the following property. Suppose we have a smooth solution to the Ricci flow $(g_{ij})_t = -2R_{ij}$, $0 \leq t \leq \varepsilon^2$, and assume that at $t = 0$ we have

$$\text{Ric}_{g_0}(x) \geq -\delta^2 g_0 \text{ on } B_1(x_0) \quad \& \quad |B_1(x_0)|_{g_0} \geq (1 - \delta) \omega_n.$$

Then $|Rm|(x, t) \leq \alpha t^{-1} + \varepsilon^{-2}$ for $0 < t \leq \varepsilon^2$, $d_{g_t}(x, x_0) < \varepsilon$.

RK: - From Bishop Gromov we have $|B|_{g_0} \leq (1 + C\delta) \omega_n$, so the condition $|B|_{g_0} \geq (1 - \delta) \omega_n$ is an almost maximal volume assumption.

-The proof by Tian-Wang is highly technical and not at all a straightforward corollary of Perelman's Pseudolocality Theorem.

Almost euclidean isoperimetric inequality

Q: do the assumptions of Tian-Wang's Pseudo-locality imply the assumptions of Perelman's Pseudo-Locality? I.E.

$Ric_{g_0}(x) \geq -\delta^2 g_0$ & $|B|_{g_0} \geq (1 - \delta) \omega_n \stackrel{?}{\Rightarrow} |\partial\Omega|_{g_0}^n \geq (1 - \varepsilon) c_n |\Omega|_{g_0}^{n-1}$
for all $\Omega \subset B_\varepsilon(x_0)$.

Almost euclidean isoperimetric inequality

Q: do the assumptions of Tian-Wang's Pseudo-locality imply the assumptions of Perelman's Pseudo-Locality? I.E.

$Ric_{g_0}(x) \geq -\delta^2 g_0$ & $|B|_{g_0} \geq (1 - \delta)\omega_n \stackrel{?}{\Rightarrow} |\partial\Omega|_{g_0}^n \geq (1 - \varepsilon) c_n |\Omega|_{g_0}^{n-1}$
for all $\Omega \subset B_\varepsilon(x_0)$.

THM[Cavalletti-M. IMRN '18] For every $N \in [2, \infty) \cap \mathbb{N}$ there exist $\bar{\varepsilon}_N, \bar{\delta}_N, C_N > 0$ such that the next holds.

Let (M, g) be a smooth N -dim. Riem. manifold and let $\bar{x} \in M$.

Assume that $B_1(\bar{x})$ is rel. compact and for some $\delta \in [0, \bar{\delta}_N]$

$$Ric_g \geq -\delta^2 g \text{ on } B_1(\bar{x}) \quad \& \quad |B_1(\bar{x})| \geq (1 - \delta)\omega_N$$

Almost euclidean isoperimetric inequality

Q: do the assumptions of Tian-Wang's Pseudo-locality imply the assumptions of Perelman's Pseudo-Locality? I.E.

$Ric_{g_0}(x) \geq -\delta^2 g_0$ & $|B|_{g_0} \geq (1 - \delta)\omega_n \stackrel{?}{\Rightarrow} |\partial\Omega|_{g_0}^n \geq (1 - \varepsilon)c_n|\Omega|_{g_0}^{n-1}$
for all $\Omega \subset B_\varepsilon(x_0)$.

THM[Cavalletti-M. IMRN '18] For every $N \in [2, \infty) \cap \mathbb{N}$ there exist $\bar{\varepsilon}_N, \bar{\delta}_N, C_N > 0$ such that the next holds.

Let (M, g) be a smooth N -dim. Riem. manifold and let $\bar{x} \in M$. Assume that $B_1(\bar{x})$ is rel. compact and for some $\delta \in [0, \bar{\delta}_N]$

$$Ric_g \geq -\delta^2 g \text{ on } B_1(\bar{x}) \quad \& \quad |B_1(\bar{x})| \geq (1 - \delta)\omega_N$$

Then for every subset $E \subset B_{\varepsilon_N}(\bar{x})$:

$$|\partial E|_g \geq N\omega_N^{1/N}(1 - C_N\delta) |E|_g^{\frac{N-1}{N}}.$$

Almost euclidean isoperimetric inequality

Q: do the assumptions of Tian-Wang's Pseudo-locality imply the assumptions of Perelman's Pseudo-Locality? I.E.

$Ric_{g_0}(x) \geq -\delta^2 g_0$ & $|B|_{g_0} \geq (1 - \delta)\omega_n \stackrel{?}{\Rightarrow} |\partial\Omega|_{g_0}^n \geq (1 - \varepsilon) c_n |\Omega|_{g_0}^{n-1}$
for all $\Omega \subset B_\varepsilon(x_0)$.

THM[Cavalletti-M. IMRN '18] For every $N \in [2, \infty) \cap \mathbb{N}$ there exist $\bar{\varepsilon}_N, \bar{\delta}_N, C_N > 0$ such that the next holds.

Let (M, g) be a smooth N -dim. Riem. manifold and let $\bar{x} \in M$. Assume that $B_1(\bar{x})$ is rel. compact and for some $\delta \in [0, \bar{\delta}_N]$

$$Ric_g \geq -\delta^2 g \text{ on } B_1(\bar{x}) \quad \& \quad |B_1(\bar{x})| \geq (1 - \delta)\omega_N$$

Then for every subset $E \subset B_{\varepsilon_N}(\bar{x})$:

$$|\partial E|_g \geq N\omega_N^{1/N}(1 - C_N\delta) |E|_g^{\frac{N-1}{N}}.$$

RK Actually we prove the corresponding statement more generally for a m. m. space (X, d, \mathfrak{m}) which is essentially non-branching, $CD_{loc}(-\delta, N)$ on a ball $B_1(\bar{x})$ and $\mathfrak{m}(B_1(\bar{x})) \geq (1 - \delta)\omega_N$.

Combining Colding's volume convergence Theorem (Annals of Math. '97) with the above result we get:

Combining Colding's volume convergence Theorem (Annals of Math. '97) with the above result we get:

COR[Cavalletti-M. IMRN '18] For every $N \in [2, \infty) \cap \mathbb{N}$ there exist $\bar{\varepsilon}_N, \bar{\delta}_N, C_N > 0$ such that the next holds.

Let (M, g) be a smooth N -dim. Riem. manifold and let $\bar{x} \in M$. Assume that $B_1(\bar{x})$ is rel. compact and for some $\delta \in [0, \bar{\delta}_N]$, it holds:

$$\text{Ric}_g \geq -\delta^2 g \text{ on } B_1(\bar{x}) \quad \& \quad d_{GH}(B_1(\bar{x}), B_1^{\mathbb{R}^N}) \leq \delta.$$

Combining Colding's volume convergence Theorem (Annals of Math. '97) with the above result we get:

COR[Cavalletti-M. IMRN '18] For every $N \in [2, \infty) \cap \mathbb{N}$ there exist $\bar{\varepsilon}_N, \bar{\delta}_N, C_N > 0$ such that the next holds.

Let (M, g) be a smooth N -dim. Riem. manifold and let $\bar{x} \in M$. Assume that $B_1(\bar{x})$ is rel. compact and for some $\delta \in [0, \bar{\delta}_N]$, it holds:

$$\text{Ric}_g \geq -\delta^2 g \text{ on } B_1(\bar{x}) \quad \& \quad d_{GH}(B_1(\bar{x}), B_1^{\mathbb{R}^N}) \leq \delta.$$

Then for every subset $E \subset B_{\varepsilon_N}(\bar{x})$:

$$|\partial E|_g \geq N\omega_N^{1/N}(1 - C_N\delta) |E|_g^{\frac{N-1}{N}}.$$

Combining Colding's volume convergence Theorem (Annals of Math. '97) with the above result we get:

COR[Cavalletti-M. IMRN '18] For every $N \in [2, \infty) \cap \mathbb{N}$ there exist $\bar{\varepsilon}_N, \bar{\delta}_N, C_N > 0$ such that the next holds.

Let (M, g) be a smooth N -dim. Riem. manifold and let $\bar{x} \in M$. Assume that $B_1(\bar{x})$ is rel. compact and for some $\delta \in [0, \bar{\delta}_N]$, it holds:

$$\text{Ric}_g \geq -\delta^2 g \text{ on } B_1(\bar{x}) \quad \& \quad d_{GH}(B_1(\bar{x}), B_1^{\mathbb{R}^N}) \leq \delta.$$

Then for every subset $E \subset B_{\varepsilon_N}(\bar{x})$:

$$|\partial E|_g \geq N\omega_N^{1/N}(1 - C_N\delta) |E|_g^{\frac{N-1}{N}}.$$

RK closeness in GH-distance is a priori a very weak assumption (a manifold is δ -GH close to a δ -net which is a discrete space); so it is remarkable that GH-close + lower Ricci bound \Rightarrow almost euclidean isoperimetric inequality.

Some comments, 1.

Q: Why the almost euclidean isoperimetric inequality was an open problem?

Some comments, 1.

Q: Why the almost euclidean isoperimetric inequality was an open problem?

Classical method for proving Levy-Gromov isoperimetric inequality in a nutshell:

Some comments, 1.

Q: Why the almost euclidean isoperimetric inequality was an open problem?

Classical method for proving Levy-Gromov isoperimetric inequality in a nutshell:

1. in a compact manifold, for every fixed volume v there is a minimizer Ω of the perimeter having volume v .

Some comments, 1.

Q: Why the almost euclidean isoperimetric inequality was an open problem?

Classical method for proving Levy-Gromov isoperimetric inequality in a nutshell:

1. in a compact manifold, for every fixed volume v there is a minimizer Ω of the perimeter having volume v .
2. $\partial\Omega$ is smooth (up to a singular set of large codimension) and the smooth part has constant mean curvature (the regularity is now classical but it is not trivial at all!).

Some comments, 1.

Q: Why the almost euclidean isoperimetric inequality was an open problem?

Classical method for proving Levy-Gromov isoperimetric inequality in a nutshell:

1. in a compact manifold, for every fixed volume v there is a minimizer Ω of the perimeter having volume v .
2. $\partial\Omega$ is smooth (up to a singular set of large codimension) and the smooth part has constant mean curvature (the regularity is now classical but it is not trivial at all!).
3. Using the regularity of $\partial\Omega$ (crucial: regular part has CMC) perform computations \rightsquigarrow get a lower bound on $|\partial\Omega|$ (so a fortiori get a lower bound of the perimeter of any set since Ω is a minimizer).

Some comments, 1.

Q: Why the almost euclidean isoperimetric inequality was an open problem?

Classical method for proving Levy-Gromov isoperimetric inequality in a nutshell:

1. in a compact manifold, for every fixed volume v there is a minimizer Ω of the perimeter having volume v .
2. $\partial\Omega$ is smooth (up to a singular set of large codimension) and the smooth part has constant mean curvature (the regularity is now classical but it is not trivial at all!).
3. Using the regularity of $\partial\Omega$ (crucial: regular part has CMC) perform computations \rightsquigarrow get a lower bound on $|\partial\Omega|$ (so a fortiori get a lower bound of the perimeter of any set since Ω is a minimizer).

DIFFICULTY If we want to prove an AE isoperimetric ineq on $B_1(\bar{x})$

- ▶ A minimizing sequence for the perimeter can approach $\partial B_1(\bar{x})$ and so the minimizer Ω will hit $\partial B_1(\bar{x})$.

DIFFICULTY If we want to prove an AE isoperimetric ineq on $B_1(\bar{x})$

- ▶ A minimizing sequence for the perimeter can approach $\partial B_1(\bar{x})$ and so the minimizer Ω will hit $\partial B_1(\bar{x})$.
- ▶ On the contact region we have an obstacle problem, regularity is more tricky (partial regularity by Caffarelli in 70ies); in any case $\partial\Omega \cap \partial B_1(\bar{x})$ may not have constant mean curvature (if $\partial B_1(\bar{x})$ has not)

DIFFICULTY If we want to prove an AE isoperimetric ineq on $B_1(\bar{x})$

- ▶ A minimizing sequence for the perimeter can approach $\partial B_1(\bar{x})$ and so the minimizer Ω will hit $\partial B_1(\bar{x})$.
- ▶ On the contact region we have an obstacle problem, regularity is more tricky (partial regularity by Caffarelli in 70ies); in any case $\partial\Omega \cap \partial B_1(\bar{x})$ may not have constant mean curvature (if $\partial B_1(\bar{x})$ has not)
- ▶ \rightsquigarrow not in good shape to perform computations of Levy-Gromov on the minimizer.

DIFFICULTY If we want to prove an AE isoperimetric ineq on $B_1(\bar{x})$

- ▶ A minimizing sequence for the perimeter can approach $\partial B_1(\bar{x})$ and so the minimizer Ω will hit $\partial B_1(\bar{x})$.
- ▶ On the contact region we have an obstacle problem, regularity is more tricky (partial regularity by Caffarelli in 70ies); in any case $\partial\Omega \cap \partial B_1(\bar{x})$ may not have constant mean curvature (if $\partial B_1(\bar{x})$ has not)
- ▶ \rightsquigarrow not in good shape to perform computations of Levy-Gromov on the minimizer.

Some comments, 3.

- ▶ **What we do:** Via 1-D localization, we prove the lower bound on the perimeter of EVERY subset, not just of the minimizers, without any regularity assumption.

Some comments, 3.

- ▶ **What we do:** Via 1-D localization, we prove the lower bound on the perimeter of EVERY subset, not just of the minimizers, without any regularity assumption.
- ▶ \rightsquigarrow One uses synthetic Ricci curvature lower bounds via optimal transport to prove a new smooth statement.

Some comments, 3.

- ▶ **What we do:** Via 1-D localization, we prove the lower bound on the perimeter of EVERY subset, not just of the minimizers, without any regularity assumption.
- ▶ \rightsquigarrow One uses synthetic Ricci curvature lower bounds via optimal transport to prove a new smooth statement.

Part 3. Some ideas of the 1D localization technique

Proof part 1: 1-D localization

Let (X, d, \mathfrak{m}) be a $CD(K, N)$ space and assume for the moment that given $E \subset X$ we can find a "1-D localization" $\{X_q\}_{q \in Q}$ of X , i.e.

1. $\{X_q\}_{q \in Q}$ is (essentially) a partition of X , i.e.
$$\mathfrak{m}(X \setminus \bigcup_{q \in Q} X_q) = 0,$$

Proof part 1: 1-D localization

Let (X, d, \mathfrak{m}) be a $CD(K, N)$ space and assume for the moment that given $E \subset X$ we can find a "1-D localization" $\{X_q\}_{q \in Q}$ of X , i.e.

1. $\{X_q\}_{q \in Q}$ is (essentially) a partition of X , i.e.
$$\mathfrak{m}(X \setminus \bigcup_{q \in Q} X_q) = 0,$$
2. $\mathfrak{m} = \int_Q \mathfrak{m}_q \alpha(dq)$, with $\alpha(Q) = 1$ and $\mathfrak{m}_q(X_q) = \mathfrak{m}_q(X) = 1$
for α -a.e. $q \in Q$
 \rightsquigarrow disintegration of \mathfrak{m} (kind of non-straight Fubini)

Proof part 1: 1-D localization

Let (X, d, \mathfrak{m}) be a $CD(K, N)$ space and assume for the moment that given $E \subset X$ we can find a "1-D localization" $\{X_q\}_{q \in Q}$ of X , i.e.

1. $\{X_q\}_{q \in Q}$ is (essentially) a partition of X , i.e.
$$\mathfrak{m}(X \setminus \bigcup_{q \in Q} X_q) = 0,$$
2. $\mathfrak{m} = \int_Q \mathfrak{m}_q \alpha(dq)$, with $\alpha(Q) = 1$ and $\mathfrak{m}_q(X_q) = \mathfrak{m}_q(X) = 1$ for α -a.e. $q \in Q$
 \rightsquigarrow disintegration of \mathfrak{m} (kind of non-straight Fubini)
3. X_q is a geodesic in X and $(X_q, |\cdot|, \mathfrak{m}_q)$ is a $CD(K, N)$ space

Proof part 1: 1-D localization

Let (X, d, \mathfrak{m}) be a $CD(K, N)$ space and assume for the moment that given $E \subset X$ we can find a "1-D localization" $\{X_q\}_{q \in Q}$ of X , i.e.

1. $\{X_q\}_{q \in Q}$ is (essentially) a partition of X , i.e.
$$\mathfrak{m}(X \setminus \bigcup_{q \in Q} X_q) = 0,$$
2. $\mathfrak{m} = \int_Q \mathfrak{m}_q \alpha(dq)$, with $\alpha(Q) = 1$ and $\mathfrak{m}_q(X_q) = \mathfrak{m}_q(X) = 1$ for α -a.e. $q \in Q$
 \rightsquigarrow disintegration of \mathfrak{m} (kind of non-straight Fubini)
3. X_q is a geodesic in X and $(X_q, |\cdot|, \mathfrak{m}_q)$ is a $CD(K, N)$ space
4. $\mathfrak{m}_q(E \cap X_q) = \mathfrak{m}(E)$, for α -a.e. $q \in Q$,

Proof part 1: 1-D localization

Let (X, d, \mathfrak{m}) be a $CD(K, N)$ space and assume for the moment that given $E \subset X$ we can find a "1-D localization" $\{X_q\}_{q \in Q}$ of X , i.e.

1. $\{X_q\}_{q \in Q}$ is (essentially) a partition of X , i.e.
$$\mathfrak{m}(X \setminus \bigcup_{q \in Q} X_q) = 0,$$
2. $\mathfrak{m} = \int_Q \mathfrak{m}_q \alpha(dq)$, with $\alpha(Q) = 1$ and $\mathfrak{m}_q(X_q) = \mathfrak{m}_q(X) = 1$ for α -a.e. $q \in Q$
 \rightsquigarrow disintegration of \mathfrak{m} (kind of non-straight Fubini)
3. X_q is a geodesic in X and $(X_q, |\cdot|, \mathfrak{m}_q)$ is a $CD(K, N)$ space
4. $\mathfrak{m}_q(E \cap X_q) = \mathfrak{m}(E)$, for α -a.e. $q \in Q$,

RK the first two assumptions are mild, the characterizing properties are the last two.

Proof part 2: “proof” of Levy-Gromov inequality

If for a given $E \subset X$ we can find a 1-D localization as above then

$$\begin{aligned} m^+(E) &:= \liminf_{\varepsilon \rightarrow 0^+} \frac{m(E^\varepsilon) - m(E)}{\varepsilon} \\ &= \liminf_{\varepsilon \rightarrow 0^+} \int_Q \frac{m_q(E^\varepsilon) - m_q(E)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \end{aligned}$$

Proof part 2: “proof” of Levy-Gromov inequality

If for a given $E \subset X$ we can find a 1-D localization as above then

$$\begin{aligned} m^+(E) &:= \liminf_{\varepsilon \rightarrow 0^+} \frac{m(E^\varepsilon) - m(E)}{\varepsilon} \\ &= \liminf_{\varepsilon \rightarrow 0^+} \int_Q \frac{m_q(E^\varepsilon) - m_q(E)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{m_q(E^\varepsilon \cap X_q) - m_q(E \cap X_q)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \end{aligned}$$

Proof part 2: “proof” of Levy-Gromov inequality

If for a given $E \subset X$ we can find a 1-D localization as above then

$$\begin{aligned} m^+(E) &:= \liminf_{\varepsilon \rightarrow 0^+} \frac{m(E^\varepsilon) - m(E)}{\varepsilon} \\ &= \liminf_{\varepsilon \rightarrow 0^+} \int_Q \frac{m_q(E^\varepsilon) - m_q(E)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{m_q(E^\varepsilon \cap X_q) - m_q(E \cap X_q)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{m_q((E \cap X_q)^\varepsilon \cap X_q) - m_q(E \cap X_q)}{\varepsilon} \alpha(dq), \\ &\quad \text{by } E^\varepsilon \cap X_q \supset (E \cap X_q)^\varepsilon \cap X_q \end{aligned}$$

Proof part 2: “proof” of Levy-Gromov inequality

If for a given $E \subset X$ we can find a 1-D localization as above then

$$\begin{aligned} m^+(E) &:= \liminf_{\varepsilon \rightarrow 0^+} \frac{m(E^\varepsilon) - m(E)}{\varepsilon} \\ &= \liminf_{\varepsilon \rightarrow 0^+} \int_Q \frac{m_q(E^\varepsilon) - m_q(E)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{m_q(E^\varepsilon \cap X_q) - m_q(E \cap X_q)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{m_q((E \cap X_q)^\varepsilon \cap X_q) - m_q(E \cap X_q)}{\varepsilon} \alpha(dq), \\ &\quad \text{by } E^\varepsilon \cap X_q \supset (E \cap X_q)^\varepsilon \cap X_q \\ &\geq \int_Q m_q^+(E \cap X_q) \alpha(dq) \end{aligned}$$

Proof part 2: “proof” of Levy-Gromov inequality

If for a given $E \subset X$ we can find a 1-D localization as above then

$$\begin{aligned} \mathfrak{m}^+(E) &:= \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}(E^\varepsilon) - \mathfrak{m}(E)}{\varepsilon} \\ &= \liminf_{\varepsilon \rightarrow 0^+} \int_Q \frac{\mathfrak{m}_q(E^\varepsilon) - \mathfrak{m}_q(E)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}_q(E^\varepsilon \cap X_q) - \mathfrak{m}_q(E \cap X_q)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}_q((E \cap X_q)^\varepsilon \cap X_q) - \mathfrak{m}_q(E \cap X_q)}{\varepsilon} \alpha(dq), \\ &\quad \text{by } E^\varepsilon \cap X_q \supset (E \cap X_q)^\varepsilon \cap X_q \\ &\geq \int_Q \mathfrak{m}_q^+(E \cap X_q) \alpha(dq) \\ &\geq \int_Q \mathcal{I}_{K,N}(\mathfrak{m}_q(E)) \alpha(dq) \quad \text{by 3. + Smooth LGI (by E. Milman)} \end{aligned}$$

Proof part 2: “proof” of Levy-Gromov inequality

If for a given $E \subset X$ we can find a 1-D localization as above then

$$\begin{aligned} \mathfrak{m}^+(E) &:= \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}(E^\varepsilon) - \mathfrak{m}(E)}{\varepsilon} \\ &= \liminf_{\varepsilon \rightarrow 0^+} \int_Q \frac{\mathfrak{m}_q(E^\varepsilon) - \mathfrak{m}_q(E)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}_q(E^\varepsilon \cap X_q) - \mathfrak{m}_q(E \cap X_q)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}_q((E \cap X_q)^\varepsilon \cap X_q) - \mathfrak{m}_q(E \cap X_q)}{\varepsilon} \alpha(dq), \\ &\quad \text{by } E^\varepsilon \cap X_q \supset (E \cap X_q)^\varepsilon \cap X_q \\ &\geq \int_Q \mathfrak{m}_q^+(E \cap X_q) \alpha(dq) \\ &\geq \int_Q \mathcal{I}_{K,N}(\mathfrak{m}_q(E)) \alpha(dq) \quad \text{by 3. + Smooth LGI (by E. Milman)} \\ &= \int_Q \mathcal{I}_{K,N}(\mathfrak{m}(E)) \alpha(dq) \quad \text{by 4.} \end{aligned}$$

Proof part 2: “proof” of Levy-Gromov inequality

If for a given $E \subset X$ we can find a 1-D localization as above then

$$\begin{aligned} \mathfrak{m}^+(E) &:= \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}(E^\varepsilon) - \mathfrak{m}(E)}{\varepsilon} \\ &= \liminf_{\varepsilon \rightarrow 0^+} \int_Q \frac{\mathfrak{m}_q(E^\varepsilon) - \mathfrak{m}_q(E)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}_q(E^\varepsilon \cap X_q) - \mathfrak{m}_q(E \cap X_q)}{\varepsilon} \alpha(dq) \quad \text{by 2.} \\ &\geq \int_Q \liminf_{\varepsilon \rightarrow 0^+} \frac{\mathfrak{m}_q((E \cap X_q)^\varepsilon \cap X_q) - \mathfrak{m}_q(E \cap X_q)}{\varepsilon} \alpha(dq), \\ &\quad \text{by } E^\varepsilon \cap X_q \supset (E \cap X_q)^\varepsilon \cap X_q \\ &\geq \int_Q \mathfrak{m}_q^+(E \cap X_q) \alpha(dq) \\ &\geq \int_Q \mathcal{I}_{K,N}(\mathfrak{m}_q(E)) \alpha(dq) \quad \text{by 3. + Smooth LGI (by E. Milman)} \\ &= \int_Q \mathcal{I}_{K,N}(\mathfrak{m}(E)) \alpha(dq) \quad \text{by 4.} = \mathcal{I}_{K,N}(\mathfrak{m}(E)). \end{aligned}$$

Proof part 3: how to construct a 1-D localization

- ▶ Recall that $m(X) = 1$, fix $E \subset X$ with $m(E) \in (0, 1)$,

Proof part 3: how to construct a 1-D localization

- ▶ Recall that $m(X) = 1$, fix $E \subset X$ with $m(E) \in (0, 1)$,
- ▶ Let $\mu_0 := \frac{\chi_E}{m(E)} m$ and $\mu_1 := \frac{1 - \chi_E}{1 - m(E)} m = \frac{\chi_{X \setminus E}}{m(X \setminus E)} m$

Proof part 3: how to construct a 1-D localization

- ▶ Recall that $m(X) = 1$, fix $E \subset X$ with $m(E) \in (0, 1)$,
- ▶ Let $\mu_0 := \frac{\chi_E}{m(E)} m$ and $\mu_1 := \frac{1 - \chi_E}{1 - m(E)} m = \frac{\chi_{X \setminus E}}{m(X \setminus E)} m$
- ▶ Consider the L^1 -optimal transport problem

$$\inf \left\{ \int_{X \times X} d(x, y) d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}$$

Proof part 3: how to construct a 1-D localization

- ▶ Recall that $m(X) = 1$, fix $E \subset X$ with $m(E) \in (0, 1)$,
- ▶ Let $\mu_0 := \frac{\chi_E}{m(E)} m$ and $\mu_1 := \frac{1 - \chi_E}{1 - m(E)} m = \frac{\chi_{X \setminus E}}{m(X \setminus E)} m$
- ▶ Consider the L^1 -optimal transport problem

$$\inf \left\{ \int_{X \times X} d(x, y) d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}$$

- ▶ By Optimal Transport techniques there exists a minimizer $\gamma \in \mathcal{P}(X \times X)$ and a 1-Lipschitz function $\varphi : X \rightarrow \mathbb{R}$ called Kantorovich potential such that, denoted

$$\Gamma := \{(x, y) \in X \times X : \varphi(x) - \varphi(y) = d(x, y)\},$$

γ is concentrated on Γ .

Proof part 3: how to construct a 1-D localization

- ▶ Recall that $m(X) = 1$, fix $E \subset X$ with $m(E) \in (0, 1)$,
- ▶ Let $\mu_0 := \frac{\chi_E}{m(E)} m$ and $\mu_1 := \frac{1 - \chi_E}{1 - m(E)} m = \frac{\chi_{X \setminus E}}{m(X \setminus E)} m$
- ▶ Consider the L^1 -optimal transport problem

$$\inf \left\{ \int_{X \times X} d(x, y) d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}$$

- ▶ By Optimal Transport techniques there exists a minimizer $\gamma \in \mathcal{P}(X \times X)$ and a 1-Lipschitz function $\varphi : X \rightarrow \mathbb{R}$ called Kantorovich potential such that, denoted

$$\Gamma := \{(x, y) \in X \times X : \varphi(x) - \varphi(y) = d(x, y)\},$$

γ is concentrated on Γ .

- ▶ The relation \sim on X given by $x \sim y$ iff $(x, y) \in \Gamma$ or $(y, x) \in \Gamma$ is an equivalence relation on X (up to an m -negligible subset) and the equivalence classes are geodesics.
 \rightsquigarrow partition of X into geodesics driven by E

Proof part 3: how to construct a 1-D localization

- ▶ Recall that $m(X) = 1$, fix $E \subset X$ with $m(E) \in (0, 1)$,
- ▶ Let $\mu_0 := \frac{\chi_E}{m(E)} m$ and $\mu_1 := \frac{1 - \chi_E}{1 - m(E)} m = \frac{\chi_{X \setminus E}}{m(X \setminus E)} m$
- ▶ Consider the L^1 -optimal transport problem

$$\inf \left\{ \int_{X \times X} d(x, y) d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}$$

- ▶ By Optimal Transport techniques there exists a minimizer $\gamma \in \mathcal{P}(X \times X)$ and a 1-Lipschitz function $\varphi : X \rightarrow \mathbb{R}$ called Kantorovich potential such that, denoted

$$\Gamma := \{(x, y) \in X \times X : \varphi(x) - \varphi(y) = d(x, y)\},$$

γ is concentrated on Γ .

- ▶ The relation \sim on X given by $x \sim y$ iff $(x, y) \in \Gamma$ or $(y, x) \in \Gamma$ is an equivalence relation on X (up to an m -negligible subset) and the equivalence classes are geodesics. \rightsquigarrow partition of X into geodesics driven by E
- ▶ More work to prove properties 3. and 4.

Why L^1 -transport?

- ▶ It is more standard to consider the L^2 -optimal transport problem: given $\mu_0, \mu_1 \in \mathcal{P}(X)$ let

$$\inf \left\{ \int_{X \times X} d(x, y)^2 d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}$$

Which defines a metric W_2 on $\mathcal{P}(X)$.

Why L^1 -transport?

- ▶ It is more standard to consider the L^2 -optimal transport problem: given $\mu_0, \mu_1 \in \mathcal{P}(X)$ let

$$\inf \left\{ \int_{X \times X} d(x, y)^2 d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}$$

Which defines a metric W_2 on $\mathcal{P}(X)$.

- ▶ If $(\mu_t)_{t \in [0,1]}$ is a W_2 -geod from μ_0 to μ_1 , then μ_t concentrates on t -intermediate points of geodesics from $\text{supp}(\mu_0)$ to $\text{supp}(\mu_1)$:

$$\mu_t(\{\gamma(t) : \gamma \text{ geod}, \gamma(0) \in \text{supp}(\mu_0), \gamma(1) \in \text{supp}(\mu_1)\}) = 1,$$

Why L^1 -transport?

- ▶ It is more standard to consider the L^2 -optimal transport problem: given $\mu_0, \mu_1 \in \mathcal{P}(X)$ let

$$\inf \left\{ \int_{X \times X} d(x, y)^2 d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}$$

Which defines a metric W_2 on $\mathcal{P}(X)$.

- ▶ If $(\mu_t)_{t \in [0,1]}$ is a W_2 -geod from μ_0 to μ_1 , then μ_t concentrates on t -intermediate points of geodesics from $\text{supp}(\mu_0)$ to $\text{supp}(\mu_1)$:

$$\mu_t(\{\gamma(t) : \gamma \text{ geod}, \gamma(0) \in \text{supp}(\mu_0), \gamma(1) \in \text{supp}(\mu_1)\}) = 1,$$

- ▶ moreover, from d^2 -monotonicity, if γ_1 and γ_2 are such geodesics with $\gamma_1(0) \neq \gamma_2(0)$ then $\gamma_1(t) \neq \gamma_2(t)$ in a.e. sense.
 \rightsquigarrow the transport at time t is given by an ess. inj. map.

Why L^1 -transport?

- ▶ It is more standard to consider the L^2 -optimal transport problem: given $\mu_0, \mu_1 \in \mathcal{P}(X)$ let

$$\inf \left\{ \int_{X \times X} d(x, y)^2 d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}$$

Which defines a metric W_2 on $\mathcal{P}(X)$.


- ▶ If $(\mu_t)_{t \in [0,1]}$ is a W_2 -geod from μ_0 to μ_1 , then μ_t concentrates on t -intermediate points of geodesics from $\text{supp}(\mu_0)$ to $\text{supp}(\mu_1)$:
 $\mu_t(\{\gamma(t) : \gamma \text{ geod}, \gamma(0) \in \text{supp}(\mu_0), \gamma(1) \in \text{supp}(\mu_1)\}) = 1$,
- ▶ moreover, from d^2 -monotonicity, if γ_1 and γ_2 are such geodesics with $\gamma_1(0) \neq \gamma_2(0)$ then $\gamma_1(t) \neq \gamma_2(t)$ in a.e. sense.
 \rightsquigarrow the transport at time t is given by an ess. inj. map.
- ▶ **BUT** it may happen $\gamma_1(s) = \gamma_2(t)$ for $s \neq t$
 \rightsquigarrow L^2 -transport does not induce an equivalence relation.

Why L^1 -transport?

- ▶ It is more standard to consider the L^2 -optimal transport problem: given $\mu_0, \mu_1 \in \mathcal{P}(X)$ let

$$\inf \left\{ \int_{X \times X} d(x, y)^2 d\gamma : \gamma \in \mathcal{P}(X \times X), (\pi_1)_\# \gamma = \mu_0, (\pi_2)_\# \gamma = \mu_1 \right\}$$

Which defines a metric W_2 on $\mathcal{P}(X)$.

- ▶ If $(\mu_t)_{t \in [0,1]}$ is a W_2 -geod from μ_0 to μ_1 , then μ_t concentrates on t -intermediate points of geodesics from $\text{supp}(\mu_0)$ to $\text{supp}(\mu_1)$:
 $\mu_t(\{\gamma(t) : \gamma \text{ geod}, \gamma(0) \in \text{supp}(\mu_0), \gamma(1) \in \text{supp}(\mu_1)\}) = 1$,
- ▶ moreover, from d^2 -monotonicity, if γ_1 and γ_2 are such geodesics with $\gamma_1(0) \neq \gamma_2(0)$ then $\gamma_1(t) \neq \gamma_2(t)$ in a.e. sense.
 \rightsquigarrow the transport at time t is given by an ess. inj. map.
- ▶ **BUT** it may happen $\gamma_1(s) = \gamma_2(t)$ for $s \neq t$
 \rightsquigarrow L^2 -transport does not induce an equivalence relation.
- ▶ On the other hand L^1 transport does induce an equivalence relation into rays where the transport is performed
 \rightsquigarrow partition of the space into $1D$ objects. 

Brief history of 1-D localization technique

The localization technique is a way to reduce an a-priori complicated high dimensional problem to a simpler 1-dimensional problem.

- ▶ In \mathbb{R}^n or \mathbb{S}^n , using the high symmetry of the space, 1-D localizations can be usually obtained via iterative bisections

Brief history of 1-D localization technique

The localization technique is a way to reduce an a-priori complicated high dimensional problem to a simpler 1-dimensional problem.

- ▶ In \mathbb{R}^n or \mathbb{S}^n , using the high symmetry of the space, 1-D localizations can be usually obtained via iterative bisections
 - ▶ Roots in a paper by Payne-Weinberger '60 about sharp estimate of 1st eigenvalue of Neumann Laplacian in compact convex sets of \mathbb{R}^n
 - ▶ Formalized by Gromov-V. Milman '87, Kannan - Lovász - Simonovits '95

Brief history of 1-D localization technique

The localization technique is a way to reduce an a-priori complicated high dimensional problem to a simpler 1-dimensional problem.

- ▶ In \mathbb{R}^n or \mathbb{S}^n , using the high symmetry of the space, 1-D localizations can be usually obtained via iterative bisections
 - ▶ Roots in a paper by Payne-Weinberger '60 about sharp estimate of 1st eigenvalue of Neumann Laplacian in compact convex sets of \mathbb{R}^n
 - ▶ Formalized by Gromov-V. Milman '87, Kannan - Lovász - Simonovits '95
- ▶ Extended by B. Klartag '14 to Riemannian manifolds via L^1 -optimal transport: no symmetry but still heavily using the smoothness of the space (estimates on 2nd fundamental form of level sets of the Kantorovich potential φ)

Brief history of 1-D localization technique

The localization technique is a way to reduce an a-priori complicated high dimensional problem to a simpler 1-dimensional problem.

- ▶ In \mathbb{R}^n or \mathbb{S}^n , using the high symmetry of the space, 1-D localizations can be usually obtained via iterative bisections
 - ▶ Roots in a paper by Payne-Weinberger '60 about sharp estimate of 1st eigenvalue of Neumann Laplacian in compact convex sets of \mathbb{R}^n
 - ▶ Formalized by Gromov-V. Milman '87, Kannan - Lovász - Simonovits '95
- ▶ Extended by B. Klartag '14 to Riemannian manifolds via L^1 -optimal transport: no symmetry but still heavily using the smoothness of the space (estimates on 2nd fundamental form of level sets of the Kantorovich potential φ)
- ▶ Extension to non-smooth spaces by Cavalletti-M. '15.

BON ANNIVERSAIRE!

THANK YOU FOR THE
ATTENTION!